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In-Use Particulate Filter State of Health Monitoring: Prognostics and Diagnostics using Radio Frequency Sensing

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# **Agenda and Presentation Outline**

PM Sensing Approaches **RF** Sensor Description and Operation **Examples: Applications for Filter Control Case Studies: Particulate Filter Diagnostics On-Road Preventative Diagnostics** Direct Detection of Filter Failures Ш. III. Diesel Filter PM Slip Detection (DPF) IV. Gasoline Filter PM Slip Detection (GPF)

**Conclusions and Outlook** 



#### Current Determination of Filter/Catalyst State is Indirect



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#### **Overview: Approaches to Filter Diagnostics**



Reactive diagnostic (after part failed)

#### Accumulation Exhaust PM Sensors

- Local Measurement: samples only a portion of engine exhaust downstream of filter.
- Non-Continuous Monitor: requires periodic regeneration.
- Reactive: monitors PM downstream of filter.
- Provides little information on soot concentrations below sensor threshold.
- Active sensing element sensor conditioning.
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Proposed RF Approach → Filter is the Sensor!



Prognostics (warning before failure)

#### **RF Measurement Approach**

- Bulk Measurement: Samples full exhaust stream passing through filter.
- Continuous Monitor: functions even with engine off (no flow).
- Proactive: sensitive to upstream emissions entering DPF / GPF.
- Direct (real-time) measurements of particulate filter state.
- Passive sensor rod antenna.

#### **RF Measurement System and Operation**

- Antenna (RF Probe), similar size to exhaust temperature sensor
- Stainless steel rod-type antenna (passive component)

## RF Control Unit Measures

- GPF/DPF Loading:
  - 1. Filter Loading
  - 2. Loading Type (PM vs. Ash)
  - 3. Spatial Distribution
  - 4. Filter Diagnostics





RF sensor responds <u>directly</u> to changes in filter dielectric properties

#### Example of RF System Operation: Transmission

- Multiple modes exist in the cavity depending on frequency of operation
- Mode structure (field profiles, direction) depend on the geometry and the frequency



#### **Resonances Provide Spatial Measurement Sensitivity**



**Electric Field Distribution and Spatial Resolution** 









### Technical Highlights: DOE Program and Partner Testing



- Develop RF sensors
- Sensor calibration
- PM/Ash loading





- Pressure drop (OE)
- Gravimetric PM
- Gravimetric Ash

- Advanced DPF materials
  - Mercedes engine test (LD)
  - Navistar engine test (HD)



- $\Delta P$  + Models
- AVL micro-soot
- Gravimetric PM/Ash

OAK RIDGE National Laboratory

CORNING

AVL benchmarking
TEOM benchmarking
Fuels & adv. combustion



- AVL micro-soot, TEOM
- Pressure drop
- Gravimetric PM/Ash



- Controls development
- DDC engine platform
- 2013+ aftertreatment





- Stock OEM controls
   (ΔP + Model)
- Gravimetric PM/Ash



- On-road fleet test
- Volvo/Mack trucks ('09 & '13)
- 24 Months total, up to 4 trucks



- Stock Volvo/Mack DPF controls
- On-road durability

8

#### Applications of RF Sensing for Particulate Filters

1. Early Warning Fault Detection and System Failure Diagnostics...



2. Fast Response "Real-Time" Particulate Filter Measurements...





3. Direct Particulate Filter Feedback Control and Reduced Engine Fuel Consumption...



#### CASE STUDY I: Heavy-Duty Diesel On-Road Evaluations



#### RF System Configuration (Mack MP-7) DSNY Fleet

- MY 2009 and MY 2010+ vehicles over four years (48 months)
- Antennas mounted directly into DPF assembly
- Control unit mounted external to aftertreatment system
- Real-time monitoring and logging of DPF loading state
- System operation with stock OEM controls



### Typical On-Road Operation and RF Sensor Response

#### Four Mack (MP-7) Fleet Vehicles









11

- OE control results in regeneration 4%-5% of time vehicles are in operation (NYC urban drive cycles)
- RF control reduces regeneration frequency and duration for these applications
  - SAE 2014-01-2349

#### Example: Early Detection BEFORE Filter Failure



RF Sensor detects high soot condition 20 hrs before uncontrolled regen and filter failure → Early Warning

 Soot loads quickly into the filter due to high engine-out PM condition



- Large exotherm upon initiation of regeneration results in DPF failure and soot slip
- Application for preventative diagnostics BEFORE emissions system failure

### CASE STUDY II: Missing Component - Filter or Catalyst



- Continuously monitors whether DPF/GPF or catalyst is present in system
- Not limited to filters: Non-intrusive monitor of DOC, SCR, LNT, TWC, NH3 slip
- Functions even when engine is off ceramic substrate results in cavity "loading"

#### RF Sensitivity to Directly Detect Structural Failures



#### CASE STUDY III: Test Cell and Engine Setup for DPF OBD



#### **Engine Dynamometer Testing**

- Testing on 1.9L GM turbo diesel engine
- Transient mode evaluation of RF response
- AVL MSS and TEOM measurements for comparison with RF and gravimetric PM







#### Measurement System and Emissions Sampling





MKS FTIR: NH<sub>3</sub>, N<sub>2</sub>O, NO, NO<sub>2</sub>, CO etc.



AVL Micro Soot Sensor: transient soot concentration measurements



DOC

DPF

TEOM 1105: real time (1 sec) direct PM mass measurement



GM 1.9L

AVL

Sartorius CP34001S: gravimetric PM mass loaded measurement

### Transient Event Monitoring – Engine-Out PM Emissions



• Derivative or RF DPF soot load measurements well-correlated to AVL MSS

• Fast response RF sensing may enable use of DPF/GPF as engine-out PM sensor



### Artificially-Induced DPF Soot Slip

10x10 Square Removed

4.0% Face Area

6 Plugs Removed 0.24% Face Area



3 inch Diameter Removed 28% Face Area

4 inch Diameter Removed 52% Face Area

End plugs from DPF outlet face removed to simulate failure modes of varying severity



### DPF Diagnostics – Failure Detection (Soot Slip)

- Tip-In events performed at regular intervals and varying DPF health conditions
- Engine operated at1500 rpm and 22% pedal with tip-ins every 3 minutes alternating between 35% (short spikes) and 40% (tall spikes) pedal positions
- Full tip-in test repeated at each DPF defect condition
- RF derivative response at each DPF health state shown



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#### Filter Failures

### DPF Diagnostics – Failure Detection (Soot Slip) Detail

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Detection of soot slip (reduced filtration efficiency) with RF sensor



Testing conducted on coated cordierite particulate filter on 1.9L GM turbo-diesel engine

### **RF Signal Correlation to Reduced PM Trapping**



0.24% Face Area



10x10 Square 4.0% Face Area



3 inch Dia. 28% Face Area



4 inch Dia. 52% Face Area

Summary of filter failure conditions evaluated for increasing soot slip

#### 0.6 0.5 ~ 0.25% outlet face surface area removed Parameter 0.4 0.3 ШĽ 0.2 0.1 0 20 10 30 40 50 60 0 Percent Endplugs Removed [%]

#### **RF** Parameter Calculation

- The first forward difference of each test condition was performed to determine the relative, instantaneous soot loading rate
- Each peak was integrated over an equivalent time span to determine the total relative soot loaded during each tip-in

#### CASE STUDY IV: GPF Evaluations on Lean GDI

#### GPF Evaluations on BMW Lean Gasoline

- BMW N43B20 4-cylinder engine from MY2008
   BMW 120i (E87) vehicle
- 2.0 liter naturally aspirated direct injection gasoline engine
- Cordierite GPF 5.2"D x 5"L, 200/8
- PM emissions sampling with AVL MSS

## BMW 120i lean gasoline vehicle on chassis dynamometer at ORNL



#### BMW N43B20 lean gasoline engine



Engine Model Number	N43B20	
Displaced volume	1995 cm <sup>3</sup>	
Number of cylinders	4	
Number of valves	4 per cylinder	
Stroke	90 mm	
Bore	84 mm	
Compression ratio	12.0:1	
Rated Power	125 kW at 6700 rpm	
Rated Torque	210 Nm at 4250 rpm	

#### **GPF Lean Stratified Tip-In Sequence**



18 20

time, min

32 34

• AVL MSS sampling before and after the GPF following repeated tests (not simultaneously)

#### GPF Tip-In Sequence with End Plugs Removed



Reduced filtration efficiency measured with RF sensor on GPF



8x8 Removed

<u>16x</u>17 Removec

24

#### GPF Steady-State Operation with End-Plugs Removed



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#### **Summary and Conclusions**

#### RF Sensing Applied to Diesel and Gasoline Particulate Filters

- RF signal transmitted through ceramic filter provides direct measurement of filter dielectric properties (filter state)
- Particulate filter soot load accuracy unaffected by ash levels in aged filters
- Direct feedback control based on DPF/GPF state
- Fast response (< 1 second) measurements of filter loading state demonstrated
- Continuous monitor over all operating conditions (even engine off)

#### Case Studies of Diagnostic Applications for RF Sensing

- **Preventative Diagnostics:** Early detection of upstream engine or system malfunctions that could lead to subsequent filter failure
  - *Heavy-duty fleet vehicle application: fault detection before DPF failure*
- **Reactive Diagnostics:** Detection of filter failure resulting in reduced trapping efficiency (soot slip) physical defects to filter
  - Gasoline & Diesel application filter failure detection via reduced PM storage
- Large failures and missing substrates detected through change in RF resonances



## Current Work and Additional Applications



Proposed DIRECT Approach:

Direct Measurement = Filter or Catalyst State

#### Conventional INDIRECT Approach:

Upstream Sensor + Downstream Sensor + Model → Estimate Filter/Catalyst State



#### Acknowledgements

This material is based upon work supported by the Department of Energy DE-EE0005653.

- •Roland Gravel, Ken Howden, and Gurpreet Singh from the DOE
- •Ralph Nine, Trevelyn Hall, and David Ollett from NETL

Commercial and National Laboratory Project Partners

- •Corning Incorporated
- •Oak Ridge National Laboratory
- Daimler Trucks NA / Detroit Diesel
- FEV
- DSNY



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### **Relevant Conference and Journal Publications**

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#### RF Accuracy over Wide Range of Operating Conditions



- HD tests on Navistar engine and LD tests on Mercedes engine at Corning
- RF accurately measures PM levels after partial regenerations

#### Accurate RF Soot Load Measurements Even with Ash



RF soot load measurements unaffected by ash unlike current approaches 32